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Absolute Stability in Delay Equations

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An equilibrium of a delay equation is said to be absolutely stable if it is asymptotically stable for all delays. This is equivalent to a certain characteristic equation's having all its roots in the left half-plane for all delays. We obtain a simple necessary and sufficient condition for absolute stability of a class of delay equations. © 1987 Academic Press, Inc.

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A standard technique for analyzing the stability of an equilibrium of a delay equation or system begins with linearization about the equilibrium. Then a characteristic equation is constructed, expressing the condition that the linearized system have a solution each component of which is a constant multiple of e^{-t} . The condition for stability of the equilibrium is that all roots of the characteristic equation have negative real part. A fixed delay τ is reflected in the characteristic equation by terms $e^{-s\tau}$. Thus the characteristic equation frequently takes the form

$$P(z) + Q(z)e^{-s\tau} = 0, \quad (1)$$

For a differential-difference equation of retarded type of order n , the characteristic equation is of the form (1) with $P(z)$ and $Q(z)$ polynomials and $P(z)$ having higher degree than $Q(z)$. For a linear system of differential-difference equations

$$u'(t) = Au(t) + Bu(t - \tau), \quad (2)$$

where u is a vector and A and B are constant square matrices, the characteristic equation is

$$\det[A + Be^{-s\tau} - zI] = 0,$$

which is of the form (1) if delay enters the system in such a way that expansion of the determinant does not produce products of exponential terms. In

many applications, the matrix B has few enough nonzero terms that this is the case.

Another example is the delayed nonlinear renewal equation

$$x(t) = \int_0^{\infty} g\{x(t-r-s)\} a(s) ds \quad (3)$$

analyzed in [3]. The linearization at an equilibrium x_c is

$$u(t) = g'(x_c) \int_0^{\infty} u(t-\tau-s) a(s) ds,$$

with characteristic equation

$$e^{-\tau z} g'(x_c) \int_0^{\infty} e^{-sz} a(s) ds = 1, \quad (4)$$

of the form (1) with

$$P(z) = 1, \quad Q(z) = -g'(x_c) \int_0^{\infty} e^{-sz} a(s) ds.$$

In each of these examples the functions $P(z)$ and $Q(z)$ are analytic in the right half-plane $\Re z \geq 0$ and $Q(z)/P(z) \rightarrow 0$ as $|z| \rightarrow \infty$ with $\Re z \geq 0$.

There are many results giving conditions under which all roots of (1) lie in the left half-plane for particular cases of functions P and Q . A recent result of Cooke and Van den Driessche [7] for a general class of equations (1) considers the location of the roots of (1) as a function of the parameter τ , $0 \leq \tau < \infty$, and shows that under the hypotheses (6), (7), (8) below there are the following three possibilities:

- (i) The equation (1) has a root in $\Re z \geq 0$ for all τ , $0 \leq \tau < \infty$.
- (ii) There is a finite number of values of τ for which roots of (1) may enter or leave $\Re z \geq 0$, but for all sufficiently large τ the equation (1) has a root in $\Re z \geq 0$.
- (iii) All roots of (1) are in $\Re z < 0$ for $0 \leq \tau < \infty$.

In the case (iii), the equilibrium whose linearization leads to the characteristic equation (1) is asymptotically stable for all delays τ . Such behavior has been called absolute stability of (1) in [8]. An early general result of Chin [6] is that the equation (2) exhibits absolute stability if and only if the eigenvalues of the matrix $(A+B)$ all have negative real part and

$$\det[A + Be^{i\nu\tau} - i\nu I] \neq 0 \quad (5)$$

for $0 \leq \nu < \infty$, $0 \leq \tau < \infty$.

Our main result is that under the conditions

$$P(z) \neq 0, \quad \Re z \geq 0 \quad (6)$$

$$\overline{P(-iy)} = P(iy), \quad \overline{Q(-iy)} = Q(iy), \quad 0 \leq y < \infty \quad (7)$$

$$|Q(iy)| < |P(iy)|, \quad 0 \leq y < \infty \quad (8)$$

$$\lim_{|z| \rightarrow \infty, \Re z > 0} |Q(z)/P(z)| = 0 \quad (9)$$

the equation (1) is absolutely stable. The proof requires only the result of [7] together with some elementary complex analysis. We shall also give an extension which applies when $P(0) + Q(0) = 0$, a case which arises in many applications but for which (8) is not satisfied.

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We begin this section with our main result.

THEOREM 1. *Let $P(z)$ and $Q(z)$ be analytic in some open set containing $\Re z \geq 0$ and satisfy the conditions (6)–(9). Then the equation (1) is absolutely stable.*

Proof. Since $P(z)$ has no zeros in $\Re z \geq 0$, the function $Q(z)/P(z)$ is analytic in $\Re z \geq 0$. On a sufficiently large semi-circle $|z| = R$ in $\Re z \geq 0$, $|Q(z)/P(z)| \leq \rho < 1$ because of (9), and $|Q(z)/P(z)| \leq \rho < 1$ on the line segment $z = iy$, $-R \leq y \leq R$ because of (8). Now, by the maximum modulus principle, $|Q(z)/P(z)| < 1$ in every large semi-circle in the right half-plane. But $|e^{z\tau}| \geq 1$ in the right half-plane, and since (1) is equivalent to

$$-\frac{Q(z)}{P(z)} = e^{z\tau},$$

there can be no root of (1) in the right half-plane for any $\tau \geq 0$.

For the characteristic equation $(a - z) + be^{-z\tau} = 0$, where $P(z) = a - z$, $Q(z) = b$, the condition that $P(z)$ have no zeros in $\Re z \geq 0$ is $a < 0$, and the condition $|Q(iy)| < |P(iy)|$ is $b^2 < a^2 + y^2$ for $0 \leq y < \infty$. Thus this equation is absolutely stable if $a < 0$ and $|b| < |a|$. This result is known; see, for example, [8], pp. 130–131]. However, even though this equation has been cited frequently in the literature on population biology, e.g., [10, p. 95] for $a = 0$, [5, 2], this absolute stability result has not become well known. For the delayed nonlinear renewal equation (3) with characteristic equation (4), it follows immediately from Theorem 1 that the condition for absolute

stability is $|g'(x_\infty)| \int_0^\infty a(s) ds < 1$ [3]. For the characteristic equation of a linear differential-difference equation of order n , the result of Theorem 1 is a theorem of Repin [12].

We shall now consider two examples, formulated in [1, pp. 446–450]. Both will lead to the question of positivity of a quartic polynomial, and we will make use of the observation that the polynomial

$$F(y) = y^4 + \beta y^2 + \gamma$$

is positive for $0 \leq y < \infty$ if and only if $\gamma > 0$ and either $\beta^2 - 4\gamma < 0$ or $\beta^2 - 4\gamma \geq 0$ and $\beta > 0$.

Our first example concerns the equation

$$(z^2 + az + b) + ce^{-\tau z} = 0, \quad (10)$$

with $P(z) = z^2 + az + b$, $Q(z) = c$. The condition that $P(z) \neq 0$ for $\Re z \geq 0$ is $a > 0$, $b > 0$. Since $P(iy) = (b - y^2) + iay$, $Q(iy) = c$, the condition $|P(iy)| > |Q(iy)|$ is $(b - y^2)^2 + a^2 y^2 > c^2$, which reduces to

$$y^4 + (a^2 - 2b)y^2 + (b^2 - c^2) > 0. \quad (11)$$

The condition (11) is satisfied if $b^2 - c^2 > 0$ and either $a^4 + 4c^2 < 4a^2b$ or $a^4 + 4c^2 \geq 4a^2b$ and $a^2 > 2b$. Thus the equation (10) is absolutely stable if and only if either $a > 0$, $b > 0$, $b^2 > c^2$, and $a^4 + 4c^2 < 4a^2b$ or $a > 0$, $b > 0$, $b^2 > c^2$, $a^4 + 4c^2 \geq 4a^2b$, and $a^2 > 2b$.

Our second example concerns the equation

$$(z^2 + az + b) + cze^{-\tau z} = 0 \quad (12)$$

with $P(z) = z^2 + az + b$, $Q(z) = cz$. The condition that $P(z) \neq 0$ for $\Re z \geq 0$ is $a > 0$, $b > 0$. Since $P(iy) = (b - y^2) + iay$, $Q(iy) = icy$, the condition $|P(iy)| > |Q(iy)|$ is $(b - y^2)^2 + a^2 y^2 > c^2 y^2$, which reduces to

$$y^4 + (a^2 - c^2 - 2b)y^2 + b^2 > 0.$$

This condition is satisfied if either

$$(a^2 - c^2 - 2b)^2 - 4b^2 = (a^2 - c^2)(a^2 - c^2 - 4b) < 0 \quad (13)$$

or

$$(a^2 - c^2)(a^2 - c^2 - 4b) > 0 \quad \text{and} \quad a^2 - c^2 - 2b > 0. \quad (14)$$

If $b > 0$ then $a^2 - c^2 > a^2 - c^2 - 4b$, and (13) can be satisfied only if $a^2 - c^2 > 0$, $a^2 - c^2 - 4b < 0$. The condition (14) is satisfied if and only if $a^2 - c^2 - 4b > 0$. Thus the equation (12) is absolutely stable if and only if

$a > 0$, $b > 0$ and either $0 < a^2 - c^2 < 4b$ or $a^2 - c^2 > 4b$, that is if and only if $a > 0$, $b > 0$, $a^2 > c^2$.

The conditions (6) and (8) are necessary for absolute stability in the sense that if (8) is violated it has been shown in [7] that there are values of τ for which (1) has roots in $\Re z \geq 0$ and if (8) and (9) hold but (6) is violated, then in any large semi-circle in the right half-plane,

$$|Q(z) e^{-\tau z}| \leq |Q(z)| < |P(z)|,$$

and Rouché's theorem shows that $P(z)$ and $P(z) + Q(z) e^{-\tau z}$ have the same number of zeros in this semi-circle, so that (1) can not be absolutely stable. On the other hand, the condition (9) is not necessary for absolute stability, as may be seen immediately by taking $P(z) = cQ(z)$ with $c > 1$.

The argument used in Theorem 1 can be extended immediately to the characteristic equation

$$P(z) + \sum_{j=1}^n Q_j(z) e^{-\tau_j z} = 0,$$

where $0 < \tau_1 < \tau_2 < \dots < \tau_n$ under the conditions (6),

$$\sum_{j=1}^n |Q_j(iy)| < |P(iy)|, \quad 0 \leq y < \infty, \quad (15)$$

$$\lim_{|z| \rightarrow \infty, \Re z > 0} \sum_{j=1}^n |Q_j(z) e^{-\tau_j z}| / |P(z)| = 0. \quad (16)$$

This gives an absolute stability condition for first order differential-difference equations with several delays.

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The condition $P(0) + Q(0) \neq 0$ in Theorem 1 implies that $z=0$ is not a root of (1) for any $\tau \geq 0$; if $z=0$ is a root of (1) then the equilibrium of the delay equation which leads to the characteristic equation (1) is not asymptotically stable. However, in some cases a characteristic equation may contain a factor z because it has been derived from an insufficiently specified problem. An integration plus an auxiliary condition, which would have the effect of removing this factor of z , is needed to describe the problem completely. An example is the characteristic equation

$$z^2 + cz + (1 - e^{-\tau})(az + b) = 0 \quad (17)$$

derived in [4] to describe the variable maturation time stage-structure population model of Nisbet and Gurney [11]; see also [9]. Here

$$P(z) = z^2 + (a + c)z + b, \quad Q(z) = -az - b,$$

and $P(0) + Q(0) = 0$. However, the proper form of the characteristic equation (17) is

$$z + c + \left(\frac{1 - e^{-z\tau}}{z} \right) (az + b) = 0; \quad (18)$$

observe that $(1 - e^{-z\tau})/z$ is analytic for $\Re z \geq 0$, but (18) is not of the form (1). In order to analyze the equation (17), and other equations which have been put in the form (1) by multiplication by a spurious factor z , it would be useful to have an absolute stability result for (1) with $P(0) + Q(0) = 0$.

THEOREM 2. *Suppose that $P(z)$ and $Q(z)$ are analytic in some open set containing $z \geq 0$, and satisfy the following conditions:*

- (i) $P(z) \neq 0, \Re z \geq 0$.
- (ii) $\overline{P(-iy)} = P(iy), \overline{Q(-iy)} = Q(iy), 0 \leq y < \infty$.
- (iii) $P(0) + Q(0) = 0$.
- (iv) $|Q(iy)| < |P(iy)|$ for $0 < y < \infty$.
- (v) $\lim_{|z| \rightarrow \infty, \Re z > 0} |Q(z)/P(z)| = 0$.

Then except for the root $z = 0$, all roots of (1) are in $\Re z < 0$ for $0 \leq \tau < \infty$.

Proof. We apply Theorem 1 to the equation

$$P(z) + \varepsilon P(z) + Q(z) e^{-z\tau} = 0 \quad (19)$$

for sufficiently small $\varepsilon > 0$. Since

$$P(0) + \varepsilon P(0) + Q(0) = \varepsilon P(0) \neq 0$$

and

$$|Q(0)| = |P(0)| < (1 + \varepsilon) |P(0)|,$$

the hypotheses of Theorem 1 are satisfied for all small $\varepsilon > 0$. Thus all roots of (19) lie in $\Re z < 0$ for sufficiently small $\varepsilon > 0$. Because the roots of (19) depend continuously on ε , the roots of (1) must lie in $\Re z \leq 0$. However, the condition (iv) guarantees that there are no roots of (1) of the form $z = iy$ with $y > 0$. Thus except for the root $z = 0$, all roots of (1) are in $\Re z < 0$.

For the equation (17), the condition that $P(z) \neq 0$ for $\Re z \geq 0$ is $a + c > 0$, $b > 0$. Since $|P(iy)|^2 = (-y^2 + b)^2 + (a + c)^2 y^2$ and $|Q(iy)|^2 = b^2 + a^2 y^2$, the

condition $|Q(iy)| < |P(iy)|$ for $y > 0$ is $y^4 + y^2(2ac + c^2 - 2b) > 0$ for $y > 0$, or $b < ac + c^2/2$. Thus, except for the (simple) root $z = 0$, all roots of (17) are in $\Re z < 0$ for $0 \leq \tau < \infty$ provided $a + c > 0$, $0 < b < ac + c^2/2$. This gives an absolute stability condition for the equation (17).

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